

# Wind Sensor: PDR Presentation Advisor: Dr. Kuh

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## Summary

**Acoustic & Ultrasonic:** 

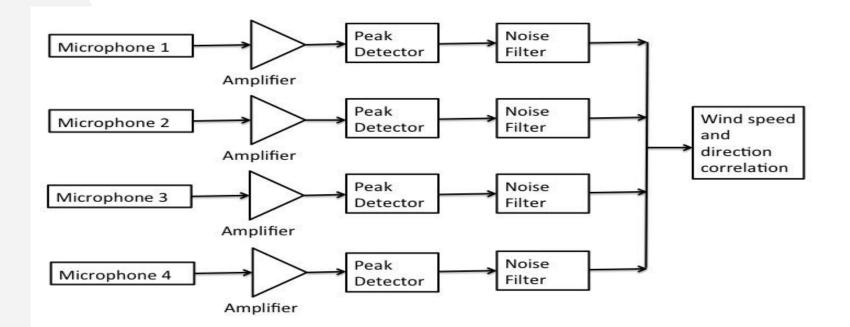
- Block Diagrams
- ► Problems
- ► Progress
- Future Tasks



# **Acoustic Wind Sensor**

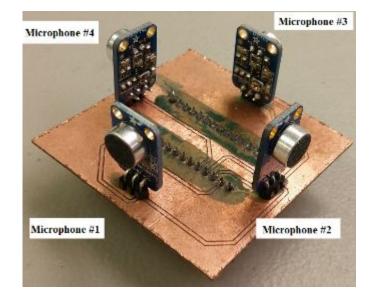
## Block Diagram

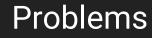






- Created a real time processing algorithm
  - Allows for continuous processing to calculate wind speed
  - ► For a single microphone
- Conducted several indoor tests
- Experimented accuracy with different means of linearizing data
  - Square root, natural log, logarithmic functions
- Began implementation of direction determination





- Syntax and algorithmic errors in code
  - Incorrect data type
  - Sign errors
- Greater inaccuracies at lower and higher wind speeds





- Work on determining wind direction with four microphones
- Explore methods to determine wind speeds outside of range
- Conduct outdoor tests to verify algorithm



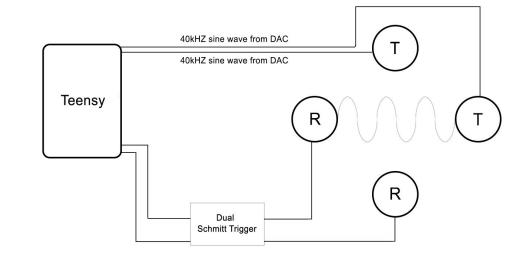


# **Ultrasonic Wind Sensor**

## Block Diagram



- Generate a timed sine wave from Teensy to power the transmitter.
- Calculate tof between transducer pairs.





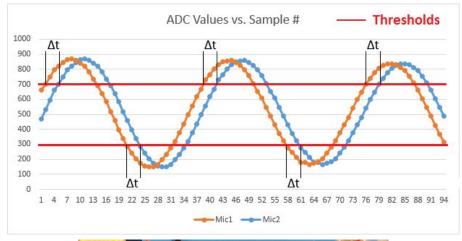
# **S**

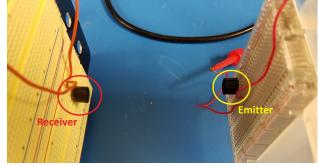
#### Software:

 Implemented an algorithm to save the threshold crossing times for a number of periods, then process the differences to derive an average propagation time

#### Hardware:

• Tested the ultrasonic emitter & receiver using a function generator and oscilloscope





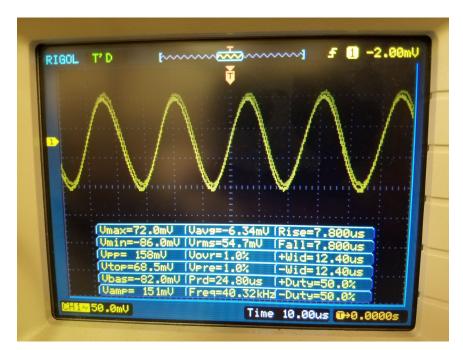
## Problems

#### **Software Problems:**

- Thresholding algorithm is error-prone (noise, skipping threshold crossing), which significantly affects the results
  - Need error filtering code

#### Hardware Problems:

- Received signal is very weak: driving the transducer with a 3.3V input, the received signal only had a voltage of 158mVpp
  - Need amplifier



## **Future Tasks**

#### Software:

- Implement error-filtering code for thresholding algorithm
- Test out current software with new parts
- Look into a high speed ADC library for Teensy

#### Hardware:

- Incorporate the new parts into our current design
- Look into methods of driving the 40kHz transducers -- may need additional power or an amplifier circuit
- Create a better testbench (instead of holding the breadboards up)

# The end.

Any questions?